

Piecewise Linear in Rates Lyapunov Functions for Complex Reaction Networks

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Combinatorial and Algebraic Approaches to Chemical Reaction Networks
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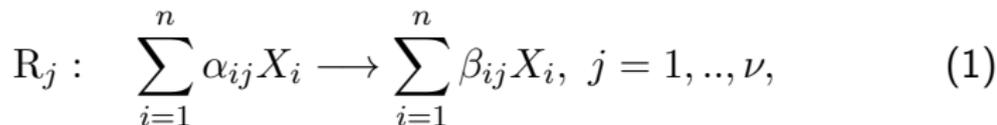
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Background

- **Complex Reaction Networks (CRNs)** is a multi-disciplinary area of research connecting engineering, mathematics, physics and systems biology.
- Large degree of **uncertainty** is a problem for the modelling of CRNs.
- Hence, analysis based solely on the **structure** is desirable, and shall be **robust** with respect to variations in the values of parameters, and reaction rates.
- Earlier work on asymptotic stability focused on the class of **weakly reversible zero deficiency networks** (Horn and Jackson 1972, Feinberg 1979).
- Angeli and Sontag (2008), Angeli et al. (2010) used **monotonicity** for establishing convergence of a class of CRNs.

Complex Reaction Networks

- A CRN is defined by a **set of species** $\mathcal{S} = \{X_1, \dots, X_n\}$, and a **set of reactions** $\mathcal{R} = \{R_1, \dots, R_\nu\}$. Each reaction is denoted as:



- The **stoichiometry matrix** is an $n \times r$ matrix which is defined as:

$$[\Gamma]_{ij} = \beta_{ij} - \alpha_{ij}.$$

ODE Formulation

The dynamics of a CRN with n species and ν reactions are described by a system of ordinary differential equations (ODEs) as:

$$\dot{x}(t) = \Gamma R(x(t)), \quad x(0) \in \bar{\mathbb{R}}_+^n \quad (2)$$

where $x(t)$ is the concentration vector evolving in the **nonnegative orthant** $\bar{\mathbb{R}}_+^n$, $\Gamma \in \mathbb{R}^{n \times \nu}$ is the stoichiometry matrix, $R(x(t)) \in \bar{\mathbb{R}}_+^\nu$ is the reaction rates vector.

In addition, the manifold $\mathcal{C}_{x_o} := (\{x(0)\} + \text{Im}(\Gamma)) \cap \bar{\mathbb{R}}_+^n$ is forward invariant, and is called the **stoichiometric compatibility class** associated with x_o .

Reaction Rates

We assume that the **reaction rate** satisfies the following:

- A1.** it is a \mathcal{C}^1 function, i.e. continuously differentiable;
- A2.** $x_i = 0 \Rightarrow R_j(x) = 0$, for all i and j such that $\alpha_{ij} > 0$;
- A3.** it is nondecreasing with respect to its reactants, i.e

$$\frac{\partial R_j}{\partial x_i}(x) \begin{cases} \geq 0 & : \alpha_{ij} > 0 \\ = 0 & : \alpha_{ij} = 0 \end{cases} .$$

- A4.** The inequality in (6) holds strictly for all $x \in \mathbb{R}_+^n$.

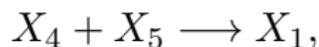
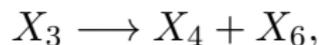
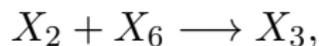
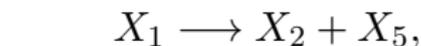
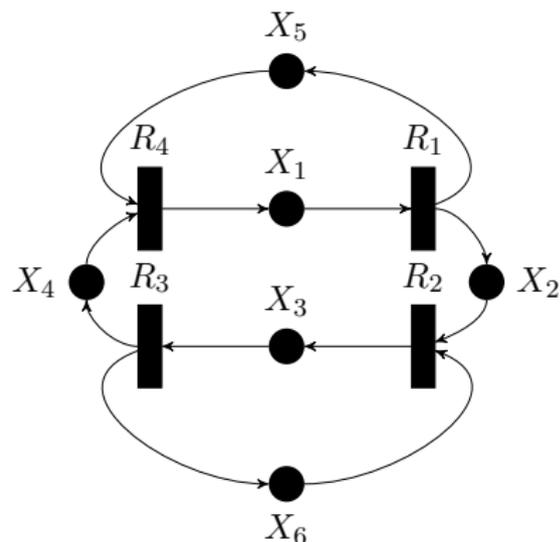
Furthermore, we assume the following:

- A6.** There are no **autocatalytic** reactions.
- A7.** There exists $v \in \ker \Gamma$ such that $v \gg 0$.

Siphons

- Let the set of output reactions of P is denoted by $\Lambda(P)$.
- A **conservation law** is some $w \gg 0$ where $w^T \Gamma = 0$.
- A nonempty set $P \subset V_S$ is called a **siphon** (Angeli et al 2007) if each input reaction associated to P is also an output reaction associated to P .
- A siphon is a **deadlock** if $\Lambda(P) = V_R$.
- A siphon or a deadlock is said to be **critical** if it does not contain a set of species corresponding to the support of a conservation law.

Example: Futile Cycle



$$\dot{x} = \begin{bmatrix} -1 & 0 & 0 & 1 \\ 1 & -1 & 0 & 0 \\ 0 & 1 & -1 & 0 \\ 0 & 0 & 1 & -1 \\ 1 & 0 & 0 & -1 \\ 0 & -1 & 1 & 0 \end{bmatrix} \begin{bmatrix} R_1(x) \\ R_2(x) \\ R_3(x) \\ R_4(x) \end{bmatrix}$$

Motivation

- Consider the following continuous PWL in Rate (PWLR) function:

$$V(x) = |R_1(x) - R_2(x)| + |R_2(x) - R_3(x)| + |R_3(x) - R_4(x)| + |R_4(x) - R_1(x)|$$

- If we are in the region $R_1(x) \geq R_2(x) \geq R_3(x) \geq R_4(x)$, then:

$$V(x) = 2(R_1(x) - R_4(x)).$$

- The time derivative can be written as:

$$\dot{V}(x) = 2 \frac{\partial R_1}{\partial x_1} \dot{x}_1 - 2 \frac{\partial R_4}{\partial x_4} \dot{x}_4 - 2 \frac{\partial R_4}{\partial x_5} \dot{x}_5$$

- Note that in that region we have a determined sign pattern:

$$\dot{x}_1 < 0, \dot{x}_4 > 0, \dot{x}_5 > 0.$$

Definition 1

Definition

Given H with $\ker H = \ker \Gamma$, let

$$\{\mathcal{W}_k\}_{k=1}^m = \{r \in \mathbb{R}^\nu : \Sigma_k H r \geq 0\}$$

, and assume that $C = [c_1^T \dots c_{m/2}^T]^T \in \mathbb{R}^{m/2 \times \nu}$. Then, $V : \mathbb{R}^n \rightarrow \mathbb{R}$ is said to be a **Piecewise Linear in Rates (PWLR)** function if it admits the representation $V(x) = \tilde{V}(R(x))$, where $\tilde{V} : \mathbb{R}^\nu \rightarrow \mathbb{R}$ is a continuous PWL function given as

$$\tilde{V}(r) = c_k^T r, \quad r \in \mathcal{W}_k, \quad k = 1, \dots, m/2, \quad (3)$$

and $c_{k_2} = -c_{k_1}$ if $\Sigma_{k_1} = -\Sigma_{k_2}$.

Defintion II

Definition

Let C as above with $0 \ll v \in \ker C$. Then, $V : \mathbb{R}^n \rightarrow \mathbb{R}$ is said to be a convex PWLR function if it admits the representation $V(x) = \tilde{V}(R(x))$, where $\tilde{V} : \mathbb{R}^\nu \rightarrow \mathbb{R}$ is a a convex PWL given by

$$\tilde{V}(r) = \max_{1 \leq k \leq m/2} |c_k^T r| = \|Cr\|_\infty. \quad (4)$$

PWLR Lyapunov Function

Definition

Given (2) with initial condition $x_o := x(0) \in \bar{\mathbb{R}}_+^n$. Let $V : \bar{\mathbb{R}}_+^n \rightarrow \bar{\mathbb{R}}_+$ be given as: $V(x) = \tilde{V}(R(x))$, where \tilde{V} is the associated PWL function. Then V is said to be a **PWLR Lyapunov Function** if it satisfies the following for all $R \in \mathcal{K}_\Gamma$,

- 1 **Positive-Definite:** $V(x) \geq 0$ for all x , and $V(x) = 0$ if and only if $R(x) \in \ker \Gamma$.
- 2 **Nonincreasing:** $\dot{V}(x) \leq 0$ for all x .

The set of networks for which there exists a PWLR Lyapunov function is denoted by \mathcal{P} .

Lyapunov's Second Method I

Theorem (Lyapunov's Second Method)

Given (2) with initial condition $x_0 \in \mathbb{R}_+^n$, and let \mathcal{C}_{x_0} as the associated stoichiometric compatibility class. Assume there exists a PWLR Lyapunov function. and suppose that $x(t)$ is bounded,

- 1 then the equilibrium set E_{x_0} is Lyapunov stable.
- 2 If, in addition, V satisfies the LaSalle's Condition, then $x(t) \rightarrow E_{x_0}$ as $t \rightarrow \infty$ (meaning that the point to set distance of $x(t)$ to E_{x_0} tends to 0). Furthermore, any isolated equilibrium relative to \mathcal{C}_{x_0} is asymptotically stable.

Lyapunov's Second Method II

If the boundedness of solution was known a priori, then the former Theorem can be strengthened to the following:

Corollary (Global Stability)

Consider a CRN in \mathcal{P} that satisfies the LaSalle condition with a given x_o . Assume that all the trajectories are bounded. If there exists $x^ \in E_{x_o}$, which is *isolated* relative to \mathcal{C}_{x_o} then it is unique, i.e., $E_{x_o} = \{x^*\}$. Furthermore, it is *globally asymptotically stable equilibrium* relative to \mathcal{C}_{x_o} .*

The LaSalle's condition can be verified via a certain graphical algorithm.

Checking Candidates: First Representation

- Recall that $\mathcal{W}_k = \{r | \Sigma_k H r \geq 0\}$.
- To ensure nonnegativity, the coefficient vector should have the representation: $c_k^T = \xi_k^T \Sigma_k H$, $\xi_k > 0$.
- The continuity constraint can be verified by requiring the existence of $\eta_{kj} \in \mathbb{R}$ for every pair of **neighboring** regions $\mathcal{W}_k, \mathcal{W}_j$ such that

$$c_k - c_j = \eta_{kj} h_{s_{kj}}.$$

- The nondecreasingness condition is met if
 - $\text{sgn}(c_{kj_1}) \text{sgn}(c_{kj_2}) \geq 0$ for any pair of reactions R_{j_1}, R_{j_2} sharing a reactant S_i . Denote $\nu_{ki} = \text{sgn}(c_{kj})$.
 - There shall exist $\lambda^{(ki)} \in \mathbb{R}^p$, with $\lambda^{(ki)} \geq 0$ such that

$$-\nu_{ki} \gamma_i^T = \lambda^{(ki)T} \Sigma_k H,$$

Checking Candidates: Second Representation

- Recall the representation $V(x) = \|CR(x)\|_\infty$.
- The nonnegativity and continuity constraints are automatically satisfied.
- The nondecreasingness condition can be similarly stated where there shall exist $\lambda^{(ki)} \in \mathbb{R}^m$, with $\lambda^{(ki)} \geq 0$ such that

$$- \nu_{ki} \gamma_i = \sum_{\ell=1}^m \lambda_\ell^{(ki)} (c_k - c_\ell),$$

Constraints on the Possible Sign Patterns

- For simplicity, assume the system has no inflow reactions.
- Recall the time-derivative in each region \mathcal{W}_k :

$$\dot{V}(x) = \sum_{j \in J_k} \sum_{i \in I_k} c_{kj} \frac{\partial R_j}{\partial x_i} \dot{x}_i \leq 0$$

Since the sign of \dot{x}_i 's is known, this induce a **sign constraints vector** $b_k \in \{\pm 1, 0\}^r$ on the coefficient vector c_k .

- Hence, The **orthogonality condition** is to require existence of $\zeta_k > 0$ such that

$$\zeta_k^T \text{diag}(b_k) u_s = 0$$

for all $0 < u_s \in \ker \Gamma$.

Constraints on the Possible Sign Patterns II

Using the previous necessary condition, a simple graphical test for the nonexistence of a PWLR Lyapunov function can be derived. It can be stated as follows:

Corollary

Given Γ . If there exists a *critical deadlock*, then $\mathcal{N}_\Gamma \notin \mathcal{P}$.

Property of the Jacobian of \mathcal{P} Networks

- We have shown that networks in \mathcal{P} with bounded trajectories and satisfying the LaSalle's condition cannot have multiple isolated stoichiometrically compatible equilibria.
- Recall that a matrix is P_0 if all its principal minors are nonnegative, Hence:

Theorem

Given Γ . If $\mathcal{N}_\Gamma \subset \mathcal{P}$, then the jacobian $-\Gamma \frac{\partial R}{\partial x}(x)$ is a P_0 matrix for all x , and for all networks in \mathcal{N}_Γ .

- It is known that a map is injective if its jacobian matrix is P . In our case, the Jacobian matrix being P_0 implies that the network **cannot admit multiple nondegenerate positive equilibria**, where no assumption on boundedness is needed (Banaji & Pantea 2014).

Construction of PWLR Lyapunov Functions for a Given Partition

- A generic partitioning matrix is given as: $H = [\Gamma^T \hat{H}^T]^T$.
- Consider sign regions $\{\mathcal{S}_\ell\}$ which are generated by Γ . Denote $q(\cdot) : k \mapsto \ell$ if $\mathcal{W}_k \subset \mathcal{S}_\ell$.
- A linear program can be stated as:

$$\begin{aligned}
 &\text{Find} && c_k, \xi_k, \zeta_k \in \mathbb{R}^\nu, \eta_{kj} \in \mathbb{R}, k = 1, \dots, \frac{m}{2}; j \in \mathcal{N}_k, \\
 &\text{subject to} && c_k^T = \xi_k^T \Sigma_k H, \\
 &&& c_k^T = \zeta_k^T \text{diag}(b_{q_k}), \\
 &&& c_k - c_j = \eta_{kj} \sigma_{ks_{kj}} h_{s_{kj}}, \\
 &&& \xi_k \geq 0, \mathbf{1}^T \xi_k > 0, \\
 &&& \zeta_{kj} \geq 0, j \in \{1, \dots, \nu\} \setminus \mathcal{I}.
 \end{aligned}$$

Remark

- A natural candidate for the partition matrix is $H = \Gamma$. Hence, we can write

$$V(x) = c_k^T R(x) = \xi_k^T \Sigma_k \Gamma R(x) = \|\text{diag}(\xi_k) \dot{x}\|_1, R(x) \in S_k.$$

- If we have additional constraint that for all k , $\xi_k = \mathbf{1}$, then the Lyapunov function considered by Maeda et al [1978]:

$$V(x) = \|\dot{x}\|_1,$$

can be recovered as a special case.

- However, there are classes of networks for which $H = \Gamma$ does not induce a PWLR Lyapunov function, while there exists a partitioning matrix \hat{H} which does.

Iterative Algorithm for Convex PWLR Functions

- Recall that for the representation $V(R(x)) = \|CR(x)\|_\infty$, the main condition is nondecreasingness.
- If we start with an initial matrix C_0 , then we devise an algorithm to **append rows** to C_0 to satisfy the condition.
- Define the **active region** and the **permissible region**:

$$\mathcal{W}_0(c_k) := \{r \in \mathbb{R}^\nu : c_k^T r \geq c_j^T r, -m_0 \leq k \leq m_0, k \neq 0\}$$

$$\mathcal{P}(c_k) := \{r \in \mathbb{R}^\nu : \nu_{ki} \gamma_i^T r \leq 0, i \in I_k\}$$

- Append rows so that $\mathcal{W}_1(c_k) \subset \mathcal{P}(c_k)$. The new rows can be define as

$$c_{m_0+i} := c_k + \nu_{ki} \gamma_i, i \in I_k.$$

- If Algorithm 1 terminates after finite number of iterations, then we have the required function.

Special Constructions

Theorem

Consider the network family \mathcal{N}_Γ . Suppose the following properties are satisfied:

- 1 $\dim(\ker \Gamma) = 1$,
- 2 $\forall X_i \in V_S$, there exists a unique output reaction,

Then,

- the following is a PWLR function for the network family \mathcal{N}_Γ :

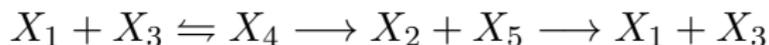
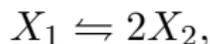
$$V(x) = \max_{1 \leq j \leq \nu} \frac{1}{v_j} R_j(x) - \min_{1 \leq j \leq \nu} \frac{1}{v_j} R_j(x), \quad (5)$$

where $v = [v_1 \dots v_\nu]^T \in \ker(\Gamma)$, $v \gg 0$.

- If the network is **conservative**, then it is persistent, i.e., $\omega(x_0) \cap \partial \mathbb{R}_+^n = \emptyset$ for all x_0 . Furthermore, if there exists an isolated equilibrium, then it is a unique globally asymptotically stable equilibrium with respect to \mathcal{C}_{x_0} .

Illustrative Example I

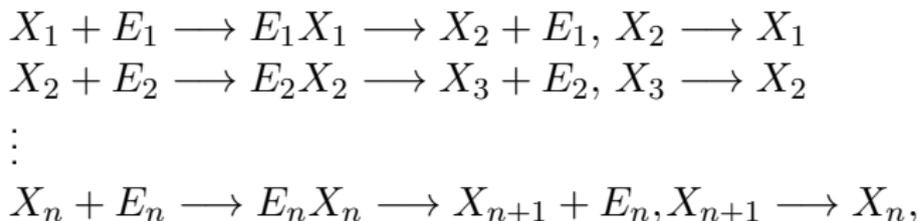
- 1 Consider the following network given by Feinberg in 1979:



- ▶ The network has a **critical deadlock** $\{X_1, X_2, X_4\}$, therefore it does not admit a PWLR Lyapunov function.
- ▶ **The deficiency-zero theorem** can be applied with Mass-Action kinetics to show that the interior equilibrium is asymptotically stable despite the existence of boundary equilibria.

Illustrative Example II

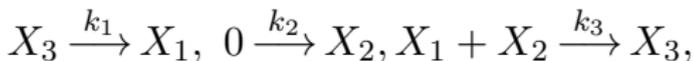
- 2 On the other hand, consider the following CRN for a given integer $n \geq 1$:



which has a deficiency n . For every n , there exists a PWLR Lyapunov function for such CRN. This shows that there is no clear relationship between our results and the notion of deficiency.

Illustrative Example III

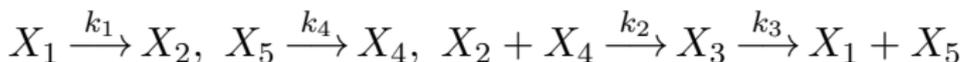
3 Consider



- ▶ The three constructions presented yield a Lyapunov function, in particular (5) is a valid one.
- ▶ However, consider the network with Mass-Action Kinetics, and let $A = x_2(0) + x_3(0)$ be the parameter corresponding to the stoichiometric compatibility class. If $A > \frac{k_2}{k_3}$, then the system trajectories are bounded and the unique equilibrium $\left(\frac{k_2 k_3}{k_3 A - k_2}, A - \frac{k_2}{k_3}, \frac{k_2}{k_3} \right)$ is globally asymptotically stable.
- ▶ When $A \leq \frac{k_2}{k_3}$, there are no equilibria in the nonnegative orthant, solutions are unbounded and approach the boundary.

Illustrative Example IV

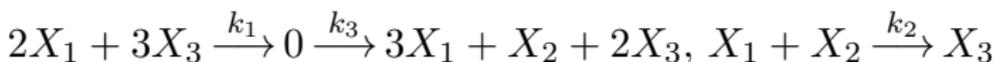
- 4 Consider the following network:



- ▶ The linear program with $H = \Gamma$ is infeasible, however, Algorithm 1 and the Special construction give rise to the PWLR function (5) with $v = \mathbf{1}$.
- ▶ Close examination indicates that if we use a partitioning matrix $\hat{H} = [1 \ 0 \ 0 \ -1]$, then the linear program will be feasible.

Illustrative Example V

- 5 Consider the following network:



The special construction does not apply. Algorithm 1 does not terminate.

However, the linear program with $H = \Gamma$ gives the following convex PWLR Lyapunov function:

$$V(x) = \max\{|6R_1(x) + R_2(x) - 7R_3(x)|, |3R_2(x) - 3R_3(x)|, |6R_1(x) - 6R_3(x)|\}.$$

Biochemical Example I

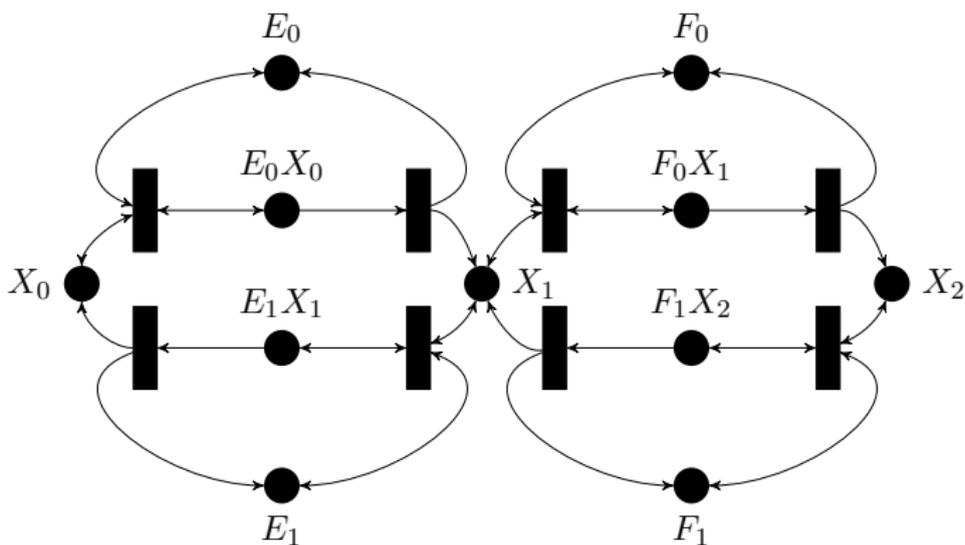
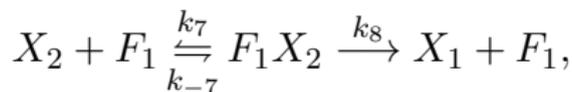
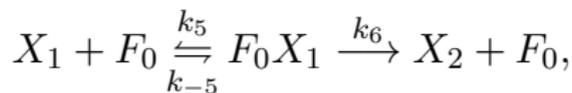
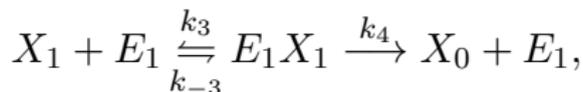
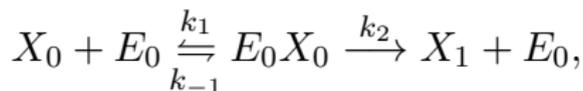


Figure: Double Futile Cycle with distinct enzymes.

Biochemical Example I



Biochemical Example II

- The PWLR function constructed can be represented as:

$$V(x) = \|\text{diag}(\xi)\dot{x}\|_1,$$

where $\xi = [2\ 2\ 2\ 1\ 1\ 1\ 1\ 1\ 1\ 1\ 1]$ and species are ordered as $X_0, X_1, X_2, \dots, F_1 X_2$.

- Existing results in the literature does not apply to this network.

Conclusion

- A new type of Lyapunov functions have been introduced for network systems, and CRNs in particular.
- Results have been provided for checking candidate PWLR Lyapunov functions.
- Several methods were introduced for their construction.
- Future direction is develop more exact characterizations for CRNs admitting PWLR Lyapunov functions:
 - ▶ Investigate the persistence of \mathcal{P} networks.
 - ▶ Develop control PWLR Lyapunov functions.

Thank you

Further details @ arxiv.org/abs/1407.0662